

Air Meshes for Robust Collision Handling

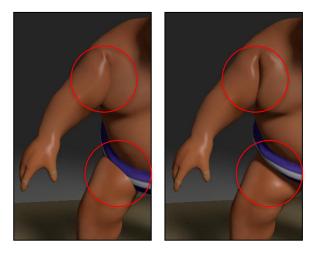
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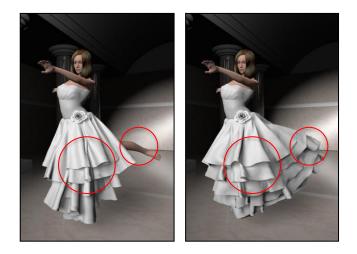


Motivation

Handling Collisions on Characters







Tissue Simulation

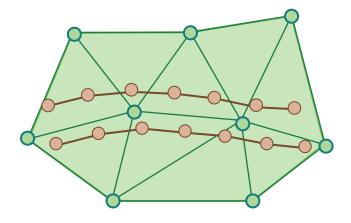
Clothing Simulation

Game Requirements

- Fast and simple
- Cannot guarantee a collision free state
 - Kinematic objects
 - Time limitation
- → Smooth recovery from any entangled state
- Suitable for GPU acceleration

Embedding e.g. [Müller et al. 2004]

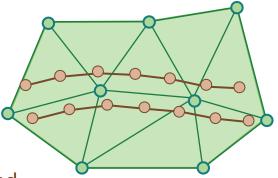




- Create enclosing tetrahedral simulation mesh
- Move cloth with the surrounding tetras

Embedding

- Pros:
 - Simple and fast
 - Untangling =
 handling inverted elements
 - No dynamic data structure for accelerating collision detection needed
- Cons:
 - Reduced flexibility (dof)
 - Influences cloth in collision free state

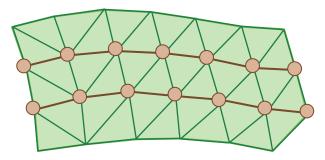




Fix Reduced Flexibility



• Let tetra vertices coincide with cloth vertices

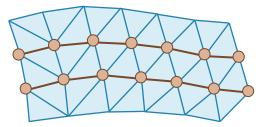


Remove Influence in Collision Free State



- Instead of elastic forces
- Use a constraint
 - Keeping the volume positive
 - Unilateral: Only active when the volume is negative!

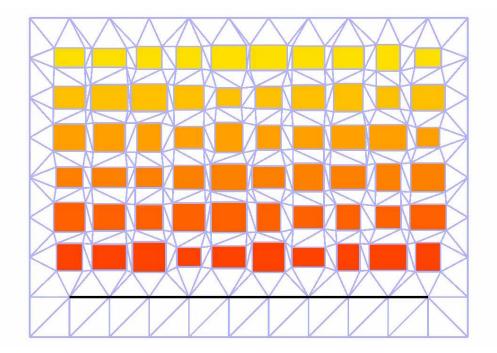
• \rightarrow Air mesh



• Handles collision detection and response

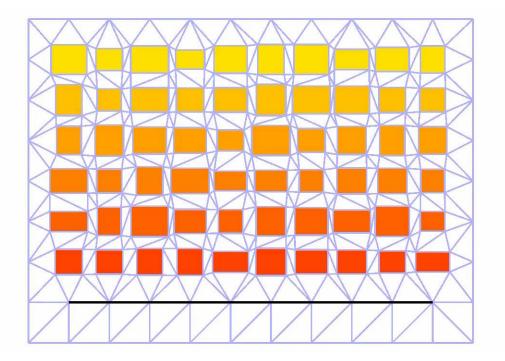
2D Example





Recovery

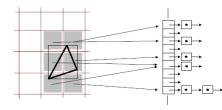


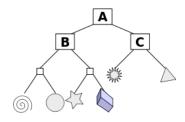


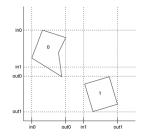
Related Work

Collision Detection









Spatial Hashing [Teschner et al. 2003] Hierarchical BVHs, BSPs, R-Trees Sweep And Prune [Baraff 1992]

• We: persistent triangle / tetrahedral mesh

Collision Response



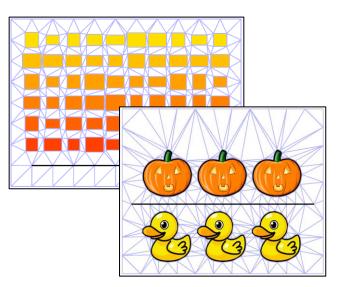
- Elastic repulsion based on proximity [Bridson et al. 2002]
- Stop motion at time of collision (CCD) by
 - Application of impulses [Bridson et al. 2002]
 - Application of position corrections [Müller et al. 2006]
- Air meshes
 - Flip inverted air elements at the end of the time step
 - No proximity measure or CCD necessary



Initial Mesh Creation



- Conforming mesh needed
 - Element boundaries line up with object boundaries
- Procedural for simple scenes
- Compute a constrained Delaunay Mesh
- TetGen [Si 2015]



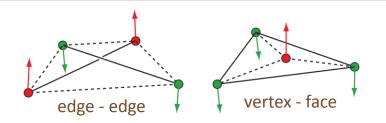
Per Element Constraint



• In a Position Based Dynamics Framework [Müller et al. 2008]

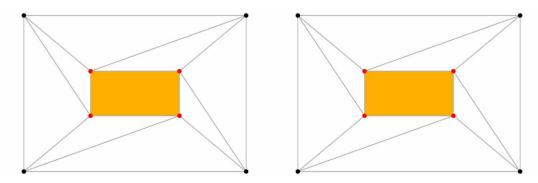
• 2D:
$$C_{air} = |(\mathbf{p}_2 - \mathbf{p}_1) \times (\mathbf{p}_3 - \mathbf{p}_1)| \ge 0$$

• 3D:
$$C_{air} = det[\mathbf{p}_2 - \mathbf{p}_1, \mathbf{p}_3 - \mathbf{p}_1, \mathbf{p}_4 - \mathbf{p}_1] \ge 0$$



Locking Problem





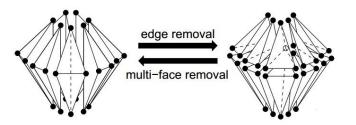
- Use kinetic pseudo triangulation Agarwal et al. [2000]
 - Provably avoids the locking problem, expensive, only in 2D
- Perform all edge flips that improve triangle quality
 - Simple, effective in practice



3D Mesh Optimization

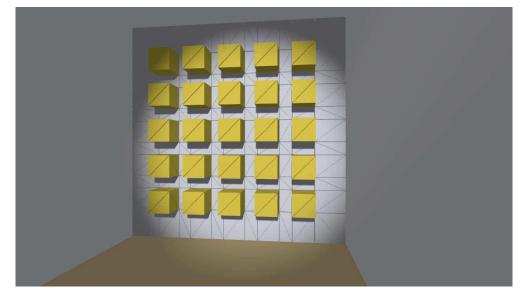


- Tetra mesh optimization is expensive
- Edge flips correspond to two complex operations



3D Mesh Optimization

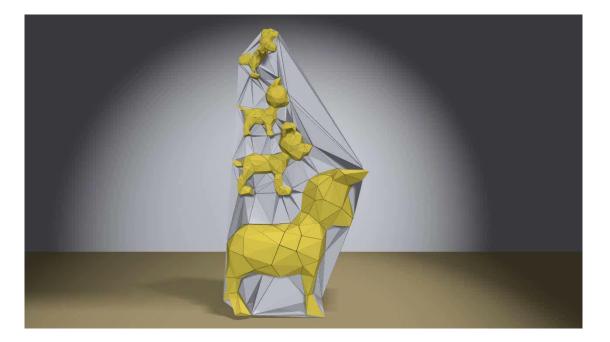




- Single thread on CPU
- 250 object elements
- 3k air elements
- Simulation: 2 ms
- Optimization: 80 ms

Irregular Mesh





With Surface Meshes





Omitting Mesh Optimization



- Locking is not a severe problem if
 - Motion mostly perpendicular to character surface
 - Minimal relative rotation and sliding

tissue





clothing



Sumo Fighter





- Single thread on CPU
- 32k tissue elements
- 1.7k air elements
- 20 fps

Sumo Fighter





Dancer







- Single thread on CPU
- 47k cloth elements
- 165k air elements
- 2 fps

Volume Conservation Constraint





Volume Inversion Constraint





Untangling





Cat Walk





- GPU implementation
- 110k triangles
- 320k air elements
- 60 fps (Titan Z)

Cat Walk





Conclusion

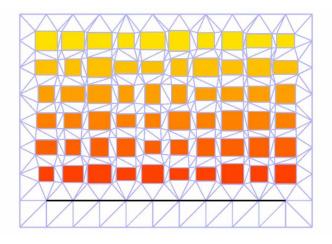


- New method for combined collision detection and response
 - Triangulate air, make sure elements do not invert
 - Solves the difficult untangling problem
- Mesh optimization is needed to prevent locking
- Simple in 2D
 - Suitable for arbitrary scenes, mobile phone games
- Complex in 3D
 - Two important applications allow omission of optimization
 - Tissue simulation and multi-layered clothing

Future Work



- Air mesh does not need to be consistent tetra mesh
 → simpler and faster way to optimize mesh?
- Dynamic creation and deletion of air elements



Questions?