

Real-Time Eulerian Water Simulation Using a Restricted Tall Cell Grid

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Main Contributions



• GPU friendly tall cell grid data structure

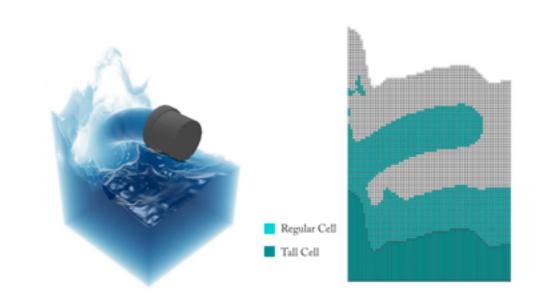
• Multigrid Poisson solver for the structure

• Modifications for advection, extrapolation



Example











Background

Foster and Fedkiw 2001

Irving et al. 2006

McAdams et al. 2010











Inviscid Incompressible Euler Equations

$$\frac{\partial \mathbf{u}}{\partial t} = -(\mathbf{u} \cdot \nabla)\mathbf{u} + \frac{\mathbf{f}}{\rho} - \frac{\nabla p}{\rho}$$

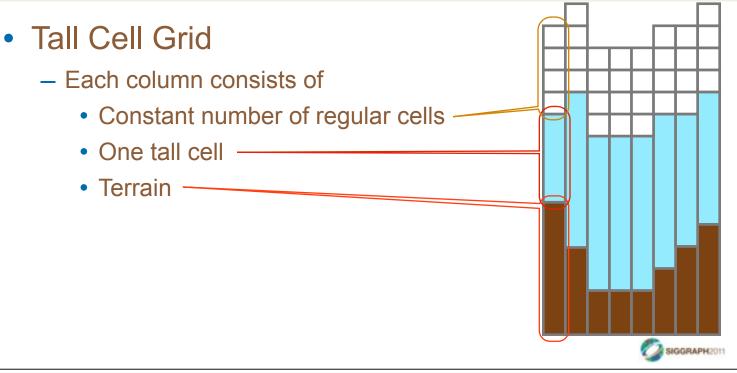
Subject to $\nabla \cdot \mathbf{u} = 0$

Inside $\phi < 0$

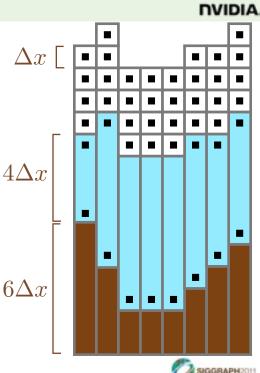
$$\frac{\partial \phi}{\partial t} = -\mathbf{u} \cdot \nabla \phi$$







- Tall Cell Grid
 - Heights are multiples of Δx
 - Physical quantities \mathbf{u}, p, ϕ and solid fraction s
 - At cell center of regular cells
 - At bottom and top of tall cells

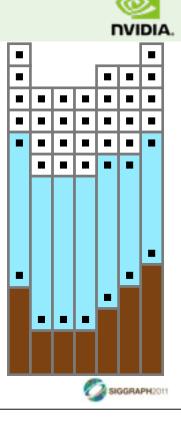


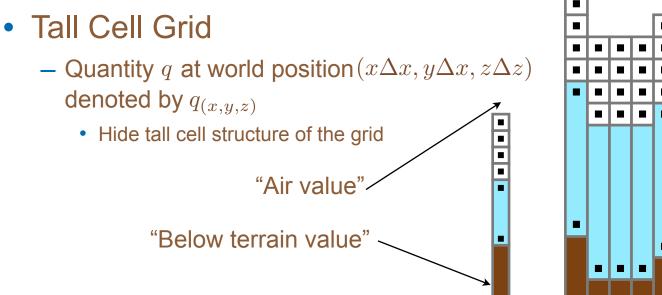


• Tall Cell Grid

- Quantity q at world position $(x\Delta x, y\Delta x, z\Delta z)$ denoted by $q_{(x,y,z)}$
 - Hide tall cell structure of the grid



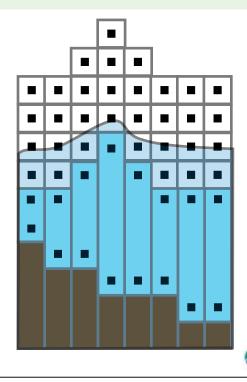






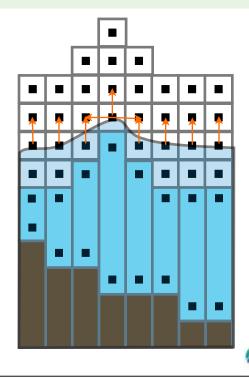


SIGGRAPH201



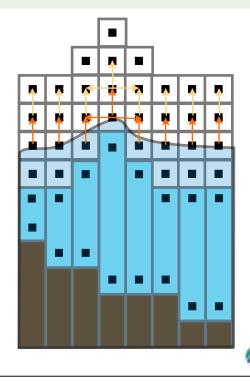


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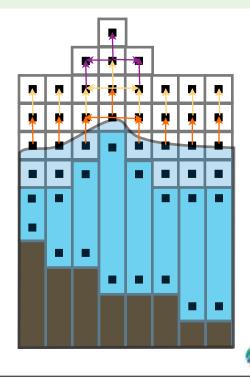


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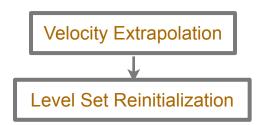


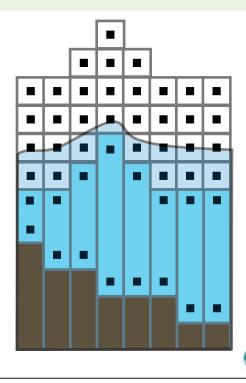


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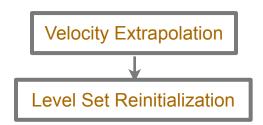


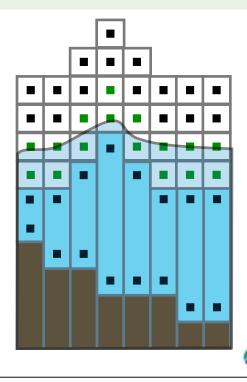




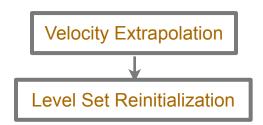


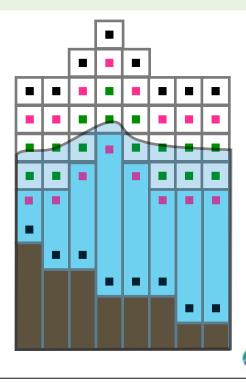




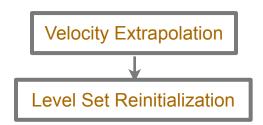


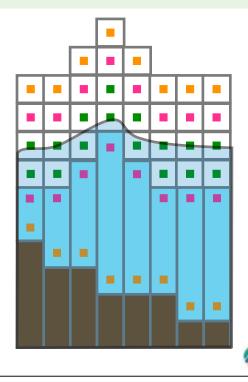




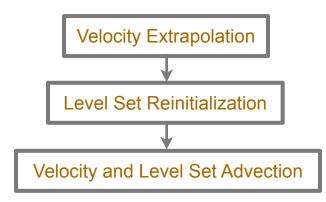


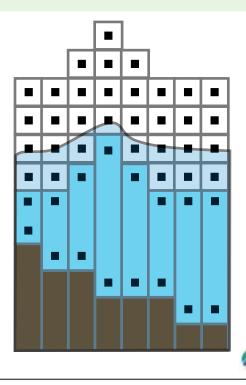


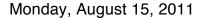




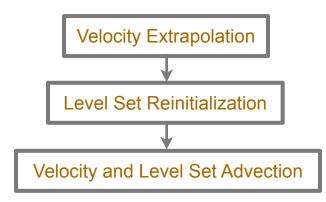


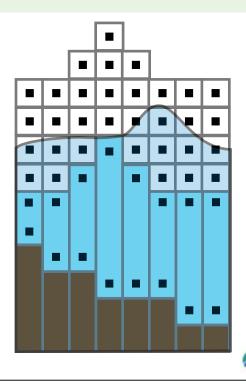






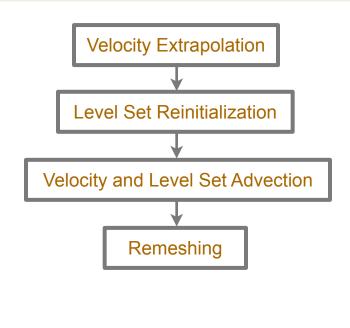


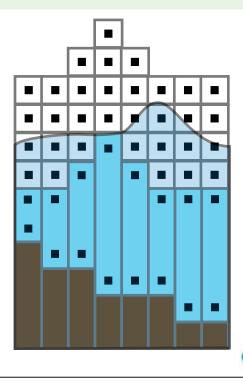






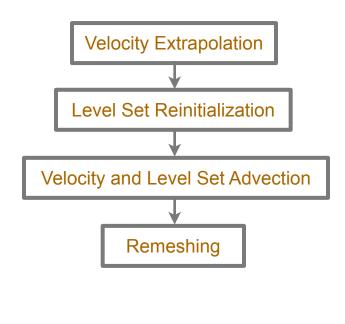
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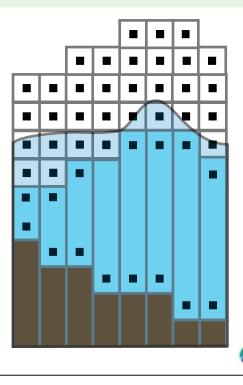






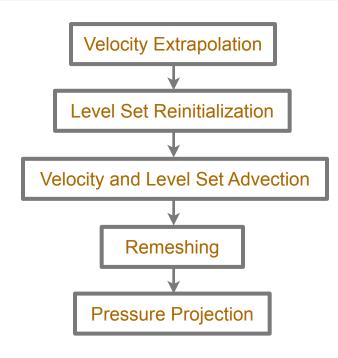
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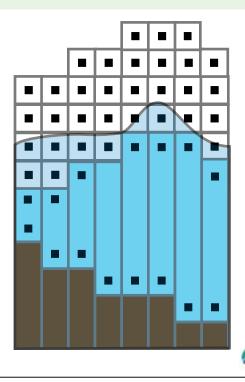






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Pressure Projection



Let u* be the velocity field before projection
 Solve

$$\nabla^2 p = \frac{\rho}{\Delta t} \nabla \cdot \mathbf{u}^*$$

- Then
$$\mathbf{u}^{n+1} = \mathbf{u}^* - \frac{\Delta t}{\rho} \nabla p$$



Pressure Projection



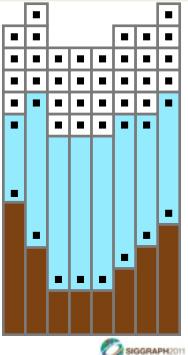
Discretized differential operators

- Divergence $(D\mathbf{u})_{i,j,k}$
- Gradient $(Gp)_{i,j,k}$
- Laplacian $(Lp)_{i,j,k}$
- Solve

$$(Lp)_{i,j,k} = \frac{\rho}{\Delta t} (D\mathbf{u}^*)_{i,j,k}$$

For all sample points

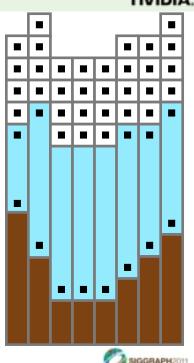
- Ghost fluid method (EF02) for free surface
- Take solid fraction into account



Pressure Projection

$$(Lp)_{i,j,k} \stackrel{\rho}{=} \frac{\rho}{\overline{\Delta t}} (D\mathbf{u}^*)_{i,j,k}$$

- Point-wise Laplacian and Divergence
 - Smaller stencils than finite volume used in Irving et al. 06
 - More regular computation, GPU friendly



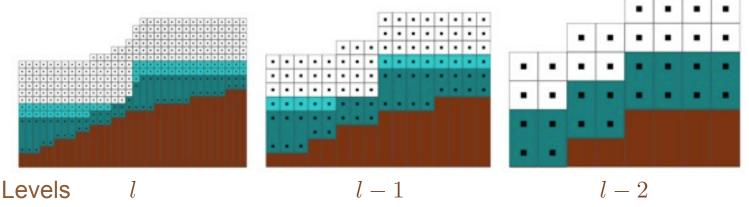


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Multigrid Solver

Construct hierarchy of grids

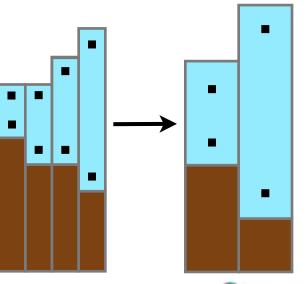
 – Down sample H, h, s, φ







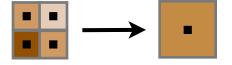
- Construct hierarchy of grids
 - Down sample H, h, s, ϕ
 - H, h cover tall liquid cells





CORAPH

- Construct hierarchy of grids
 - Down sample H, h, s, ϕ
 - s just 8-to-1 average

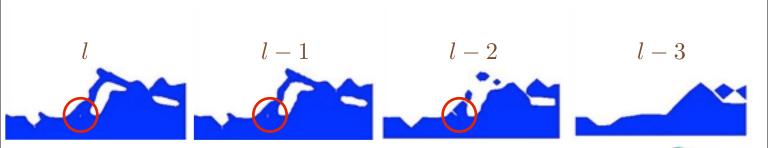






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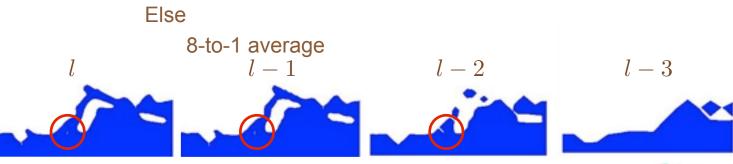
- Construct hierarchy of grids
 - Down sample H, h, s, ϕ
 - ϕ Needs special care
 - Preserve "air bubbles" in fine levels







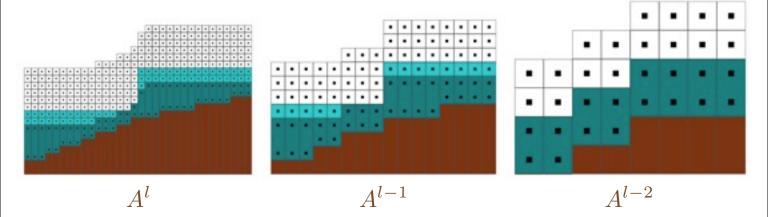
- Construct hierarchy of grids
 - Down sample H, h, s, ϕ
 - ϕ If in the finest C levels and not all 8 values are negative, Average of positive ϕ 's





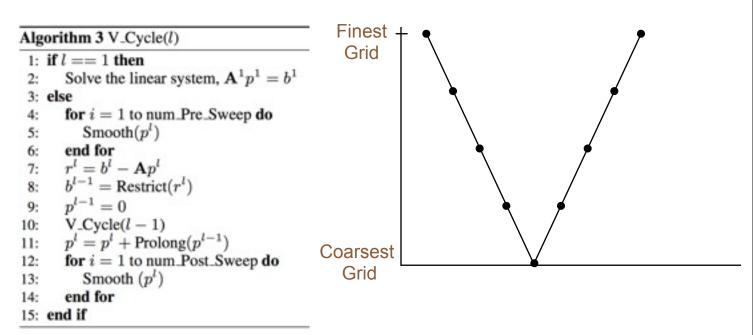






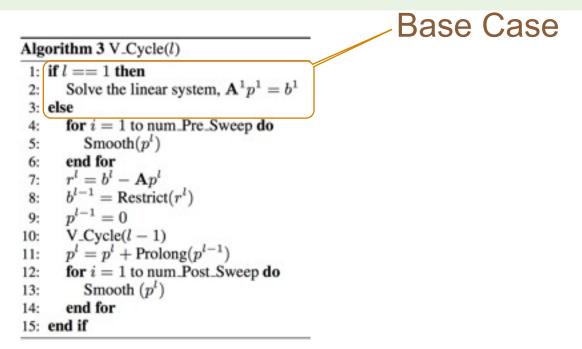












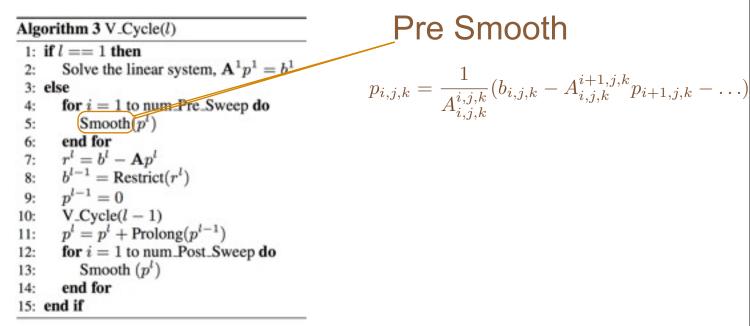




Pre Smooth Algorithm 3 V_Cycle(l) 1: if l == 1 then Solve the linear system, $\mathbf{A}^1 p^1 = b^1$ 2: $A_{i,j,k}^{i,j,k} p_{i,j,k} + A_{i,j,k}^{i+1,j,k} p_{i+1,j,k} + \ldots = b_{i,j,k}$ 3: else for i = 1 to num Pre_Sweep do 4: $Smooth(p^{l})$ 5: 6: end for 7: 8: $r^{l} = b^{l} - \mathbf{A}p^{l}$ $b^{l-1} = \text{Restrict}(r^{l})$ 9: $p^{l-1} = 0$ $V_Cycle(l-1)$ 10: $p^{l} = p^{l} + \operatorname{Prolong}(p^{l-1})$ 11: 12: for i = 1 to num_Post_Sweep do Smooth (p^t) 13: end for 14: 15: end if

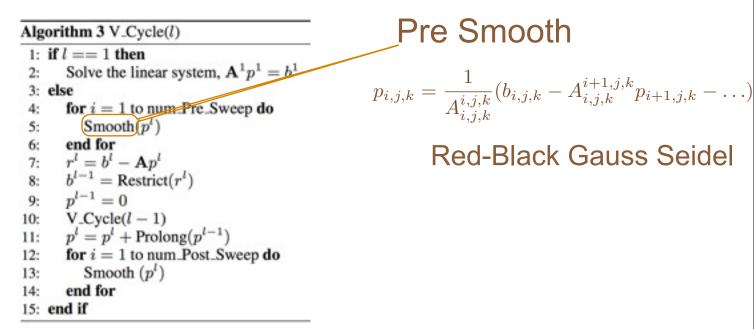
















Pre Smooth Algorithm 3 V_Cycle(l) 1: if l == 1 then Solve the linear system, $A^1p^1 = b^1$ 2: $p_{i,j,k} = \frac{1}{A_{i,j,k}^{i,j,k}} (b_{i,j,k} - A_{i,j,k}^{i+1,j,k} p_{i+1,j,k} - \ldots)$ 3: else for i = 1 to num Pre_Sweep do 4: $Smooth(p^{l})$ 5: 6: end for Red-Black Gauss Seidel 7: $r^{l} = b^{l} - \mathbf{A}p^{l}$ $b^{l-1} = \text{Restrict}(r^{l})$ 9: $p^{l-1} = 0$ $V_Cycle(l-1)$ 10: $p^{l} = p^{l} + \operatorname{Prolong}(p^{l-1})$ 11: 12: for i = 1 to num_Post_Sweep do Smooth (p^l) 13: end for 14: 15: end if

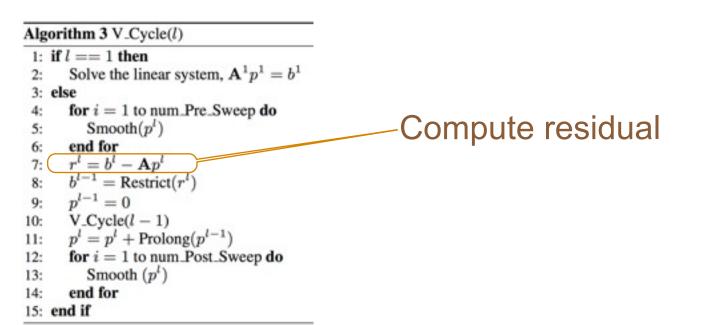




Pre Smooth Algorithm 3 V_Cycle(l) 1: if l == 1 then Solve the linear system, $A^1p^1 = b^1$ 2: $p_{i,j,k} = \frac{1}{A_{i,j,k}^{i,j,k}} (b_{i,j,k} - A_{i,j,k}^{i+1,j,k} p_{i+1,j,k} - \ldots)$ 3: else for i = 1 to num Pre_Sweep do 4: $Smooth(p^{l})$ 5: 6: end for Red-Black Gauss Seidel 7: $r^{l} = b^{l} - \mathbf{A}p^{l}$ $b^{l-1} = \text{Restrict}(r^{l})$ 9: $p^{l-1} = 0$ $V_Cycle(l-1)$ 10: $p^{l} = p^{l} + \operatorname{Prolong}(p^{l-1})$ 11: for i = 1 to num_Post_Sweep do 12: Smooth (p^l) 13: end for 14: 15: end if











Algorithm 3 V_Cycle(l)

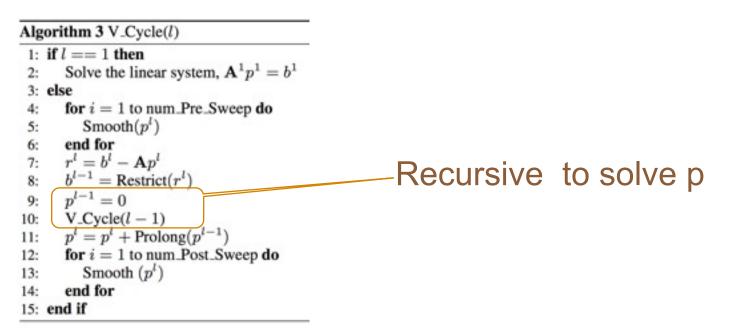
- 1: if l == 1 then
- 2: Solve the linear system, $\mathbf{A}^1 p^1 = b^1$
- 3: else
- 4: for i = 1 to num_Pre_Sweep do
- 5: $Smooth(p^l)$
- 6: end for
- 7: $r^l = b^l \mathbf{A}p^l$
- 8: $b^{l-1} = \operatorname{Restrict}(r^l)$
- 9: $p^{t-1} = 0$
- 10: V_Cycle(l − 1)
- 11: $p^l = p^l + \operatorname{Prolong}(p^{l-1})$
- 12: for i = 1 to num_Post_Sweep do
- 13: Smooth (p^l)
- 14: end for
- 15: end if

-Restrict

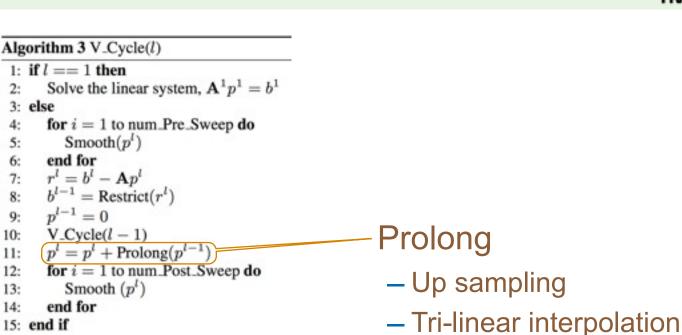
- Down sampling
- Tri-linear interpolation
 - *r* in tall cells is 0 except at top and bottom













2:

4:

5:

6: 7: 8:

9:

10:

11: 12:

13:

14:





Algorithm 3 V_Cycle(l)

1: if l == 1 then Solve the linear system, $\mathbf{A}^1 p^1 = b^1$ 2: 3: else 4: for i = 1 to num_Pre_Sweep do 5: $Smooth(p^l)$ 6: end for 7: 8: $r^l = b^l - \mathbf{A}p^l$ $b^{l-1} = \text{Restrict}(r^l)$ 9: $p^{l-1} = 0$ $V_Cycle(l-1)$ 10: $p^{l} = p^{l} + \operatorname{Prolong}(p^{l-1})$ 11: 12: for i = 1 to num_Post_Sweep do Post Smooth Smooth (p) 13: end for 14: 15: end if





Algorithm 4 Full_Cycle() 1: $p^{tmp} = p^L$ 2: $r^L = b^L - \mathbf{A} p^L$ Finest _I 3: for l = L - 1 down to 1 do Grid 4: $r^{l} = \operatorname{Restrict}(r^{l+1})$ 5: end for 6: $b^1 = r^1$ 7: Solve the linear system, $\mathbf{A}^1 p^1 = b^1$ 8: for l = 2 to L do 9: $p^l = \operatorname{Prolong}(p^{l-1})$ 10: $b^l = r^l$ Coarsest 11: V_Cycle(l) Grid 12: end for 13: $p^L = p^{tmp} + p^L$





- Three critical steps to make MG converges

 The use of Full-Cycles
 - Preserving air bubbles in the finest levels
 - Using the ghost fluid and solid fraction methods

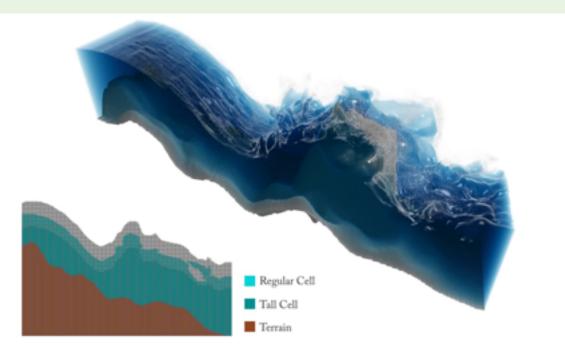




- Without tall cells,
 - Same matrix as commonly used MAC grid [FF01], [EF02], [BB07]
 - Can use our multigrid solver for those cases too

















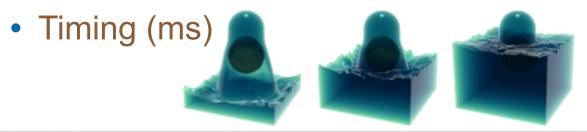
• Timing (ms)

Case	Total	VE	LA	VA	RM	PP
Manip	29.06	1.30	2.35	0.57	0.56	8.56
Tank	27.29	1.10	3.26	0.67	0.56	8.44
Flood	32.33	2.35	0.59	1.14	0.85	13.49
LightH	33.09	2.05	0.61	0.67	0.95	9.77

- More than 30fps in NVIDIA GTX 480, for all examples







256 ³ Case	IC(0) PCG				Multi-grid			
	Tol =10 ⁻⁴		Tol =10 ⁻⁸		Tol =10 ⁻⁴		Tol =10 ⁻⁸	
	Iteration	Time	Iteration	Time	Iteration Full-cycle	Time	Iteration Full-cycle	Time
Low	217	183.31	334	281.83	7	39.49	11	55.89
Mid	450	424.27	675	635.03	7	39.77	12	67.06
High	523	542.32	918	951.08	8	46.08	12	68.04

- Up to 13X faster compared to PCG



Discussions



• Drawbacks

- Divergence measured only at top & bottom of tall cells

- Slight volume gain over time
- Reduced by making sure heights of adjacent tall cells do not differ by more than *D*



Discussions



Drawbacks

- Laplacian not idempotent

- Does not eliminate divergence completely
- Not much of a problem for real-time applications

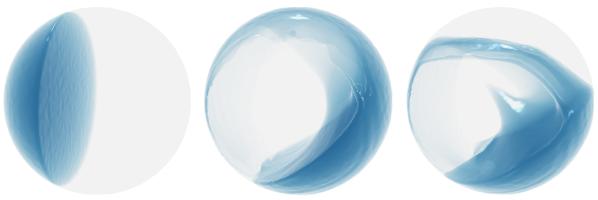


Discussion



Extension

Multigrid LCP for wall separating boundary condition



Chentanez N. and Müller M. "A Multigrid Pressure Solver Handling Separating Solid Boundary Conditions", Eurographics/ ACM SIGGRAPH Symposium on Computer Animation (SCA), 2011





Thank you for your attention!



Discussion



Future Works

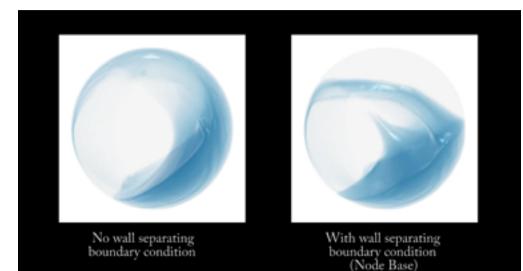
- Coupling 2D & 3D sim for larger domain
- Off-line simulation



Discussions



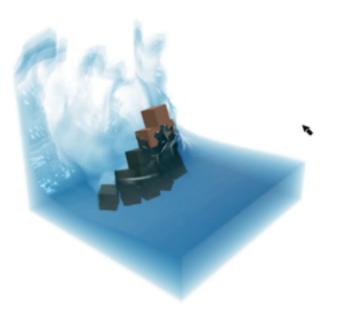
• Extension: Multigrid LCP for non-sticky liquid



Chentanez N. and Müller M. "A Multigrid Pressure Solver Handling Separating Solid Boundary Conditions", Eurographics/ ACM SIGGRAPH Symposium on Computer Animation (SCA), 2011

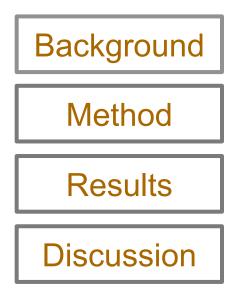






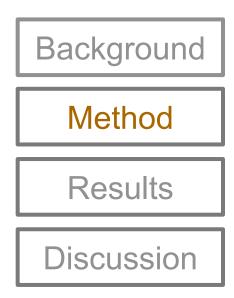


















Method

Results

Discussion





Background

Method

Results

Discussion



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Background

Fluid Simulation



Foster and Fedkiw 2001









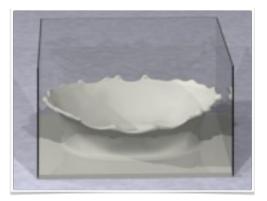




Background

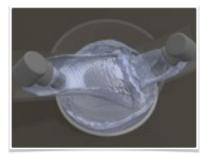


• Adaptive Grids

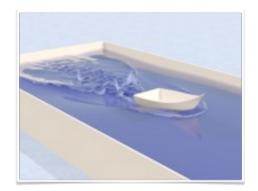


Losasso et al. 2004





Feldman et al. 2005 Chentanez et al. 2007



Irving et al. 2006



Background

Multigrid

Molemaker et al. 2008

Zhu et al. 2010

Lentine et al. 2010

McAdams et al. 2010







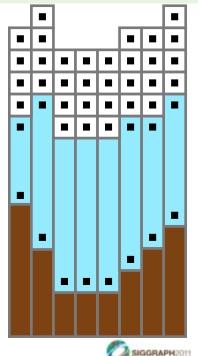
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Discretization

- Tall Cell Grid
 - Heights stored as 2D array of size (B_x, B_z)
 - Terrain height $H_{i,j}$
 - Tall cell height $h_{i,j}$





Discretization

- Tall Cell Grid
 - Quantity q stored as 3D array $q_{i,j,k}$
 - Size $(B_x, B_y + 2, B_z)$
 - B_x and B_z number of cells in x, z axes
 - B_y number of regular cells in y axis

